

Fig- 2

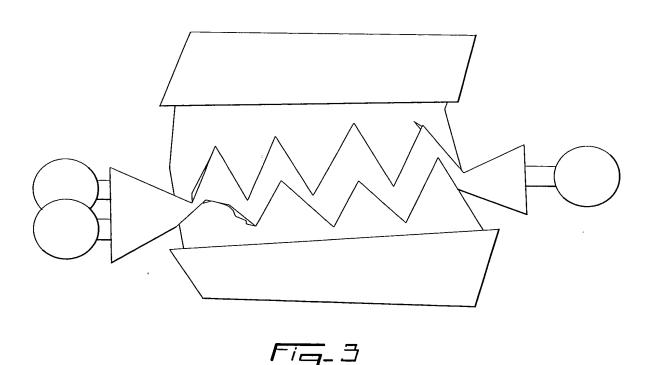


Fig-4A



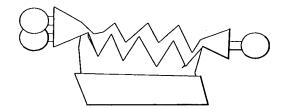
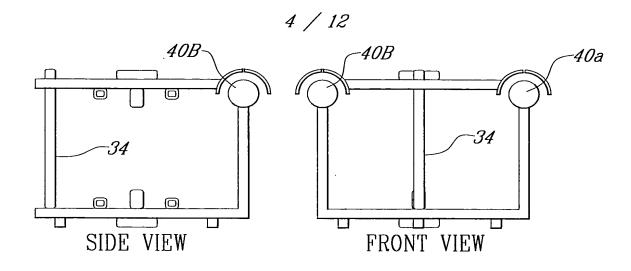


Fig-40





*Fig- 5*A

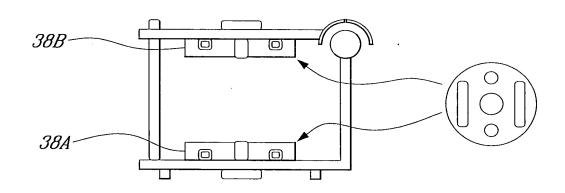
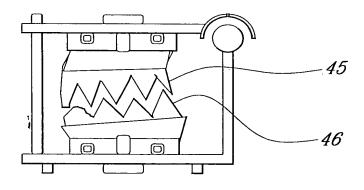
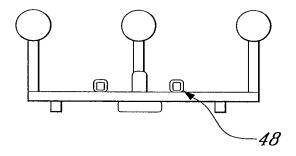


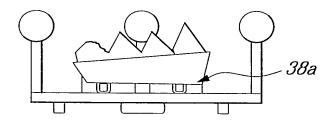
Fig- 5B



<u>Fig-</u>50



*Fig- 6*A



<u>Fig-</u>68

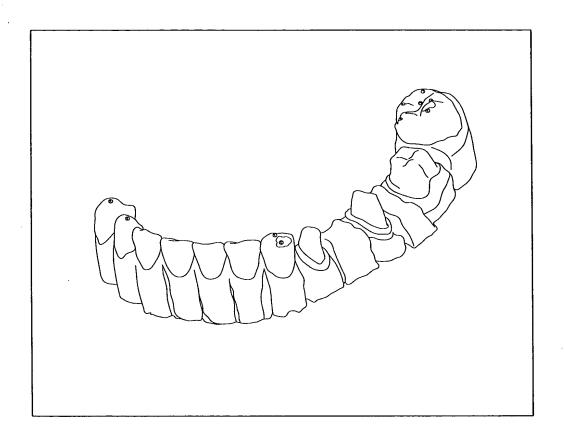
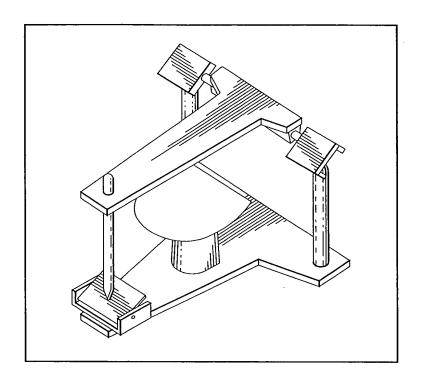
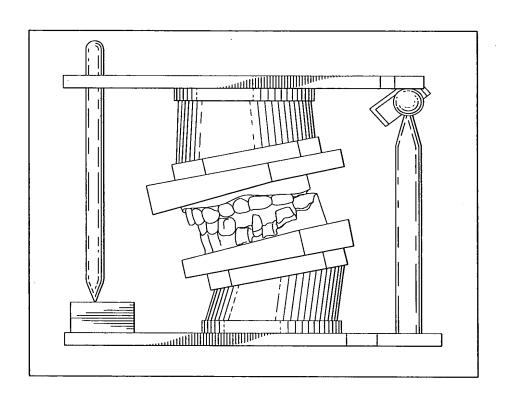
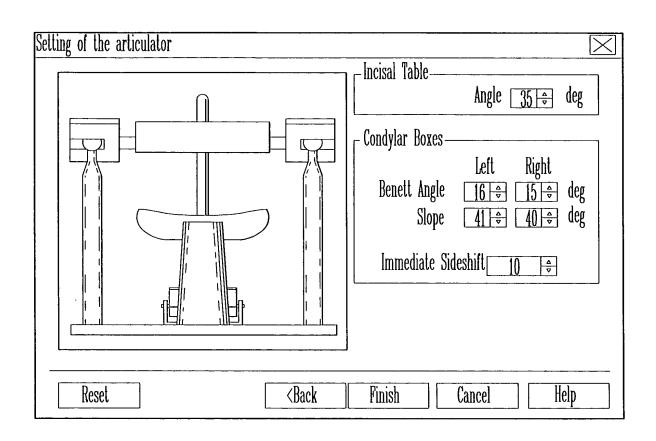


Fig- 7



<u> Fig-</u> 8

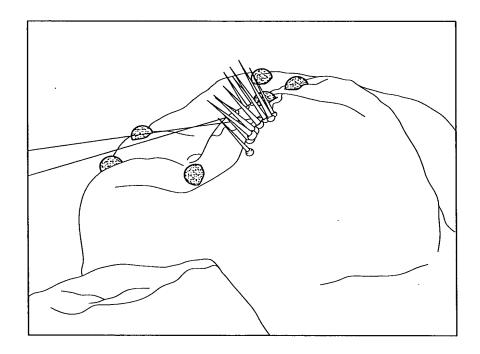




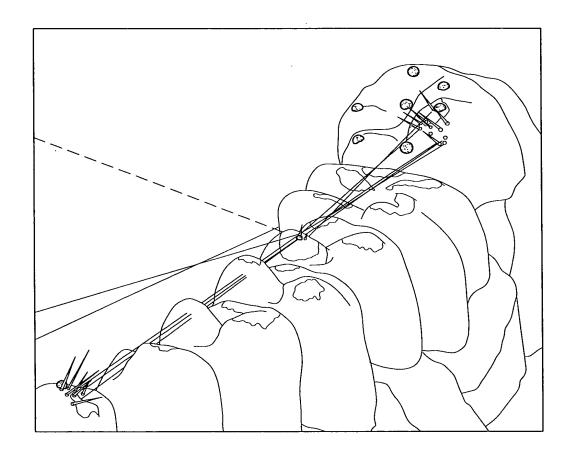
*Fig-* 10

Movement of the articulator	$\boxtimes$
	Path  ✓ Left Laterality 3500 ♣  ✓ Right Laterality 3500 ♣  ✓ Portrusion 2000 ♣  ✓ Surface exploration  ✓ Optimal Speed  ✓ Optimal Precision
(Back	Finish Cancel Help

<u>Fig-</u>11



<u>Fig-</u>12



<u>Fi</u>g-13